Degree competences to which the subject contributes

At the end of the course the student will be able to:

1. To acquire basic skills in modeling dynamic systems.
2. To define and know how to apply the general methods of systems analysis.
3. To define and know how to apply the general methods of designing control systems in continuous time.
4. To know how to configure and tune different types of controllers used in the industry.
5. Teamwork.
6. Manage information resources in the field of control systems.

**Study load**

<table>
<thead>
<tr>
<th>Total learning time: 150h</th>
<th>Hours large group:</th>
<th>45h</th>
<th>30.00%</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Hours medium group:</td>
<td>0h</td>
<td>0.00%</td>
</tr>
<tr>
<td></td>
<td>Hours small group:</td>
<td>15h</td>
<td>10.00%</td>
</tr>
<tr>
<td></td>
<td>Guided activities:</td>
<td>0h</td>
<td>0.00%</td>
</tr>
<tr>
<td></td>
<td>Self study:</td>
<td>90h</td>
<td>60.00%</td>
</tr>
</tbody>
</table>
# Content

<table>
<thead>
<tr>
<th>1. Introduction to feedback control systems</th>
<th>Learning time: 10h</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Theory classes: 3h</td>
</tr>
<tr>
<td></td>
<td>Practical classes: 2h</td>
</tr>
<tr>
<td></td>
<td>Self study : 5h</td>
</tr>
</tbody>
</table>

**Description:**

<table>
<thead>
<tr>
<th>2. Models of dynamic systems</th>
<th>Learning time: 30h</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Theory classes: 7h 30m</td>
</tr>
<tr>
<td></td>
<td>Laboratory classes: 2h</td>
</tr>
<tr>
<td></td>
<td>Self study : 20h 30m</td>
</tr>
</tbody>
</table>

**Description:**

<table>
<thead>
<tr>
<th>3. Analysis of time domain systems</th>
<th>Learning time: 30h</th>
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</thead>
<tbody>
<tr>
<td></td>
<td>Theory classes: 9h</td>
</tr>
<tr>
<td></td>
<td>Laboratory classes: 3h</td>
</tr>
<tr>
<td></td>
<td>Self study : 18h</td>
</tr>
</tbody>
</table>

**Description:**
### 4. Stability of linear systems

**Learning time:** 20h  
Theory classes: 6h  
Laboratory classes: 2h  
Self study: 12h

**Description:**  

### 5. Root locus method

**Learning time:** 10h  
Theory classes: 3h  
Laboratory classes: 2h  
Self study: 5h

**Description:**  
Concept of the root locus. Application of the root locus method to the analysis and design of control systems.

### 6. Controllers

**Learning time:** 40h  
Theory classes: 10h 30m  
Laboratory classes: 3h  
Self study: 26h 30m

**Description:**  
Integral action "antiwindup". Controllers with two degrees of freedom: PI-D and I-PD controller.  
Empirical and analytical tuning of controllers.  
Controller by state vector feedback: controllability concept.

### Qualification system

Partial controls (2): 30%  
Last control: 40%  
Practices: 15%  
Others test/projects: 10%  
Generic competition "Teamwork": 5%

In this subject will schedule a reassessment
### Regulations for carrying out activities

The written tests take place within the class schedule. Practical tests carried out in the laboratory.

### Bibliography

**Basic:**


**Complementary:**
