820230 - TCEIA - Control Techniques

Coordinating unit: 295 - EEBE - Barcelona East School of Engineering
Teaching unit: 707 - ESAII - Department of Automatic Control
Academic year: 2017
Degree: BACHELOR'S DEGREE IN INDUSTRIAL ELECTRONICS AND AUTOMATIC CONTROL ENGINEERING (Syllabus 2009). (Teaching unit Compulsory)
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ECTS credits: 6
Teaching languages: Spanish

Teaching staff
Coordinator: José Mª Huerta Sánchez
Others: Beatriz Giraldo Giraldo

Prior skills
Automatic regulation

Requirements
Automatic regulation

Degree competences to which the subject contributes

Specific:
CEEIA-26. Understand automatic regulation and control techniques and their application to industrial automation.

Transversal:
1. TEAMWORK - Level 3. Managing and making work groups effective. Resolving possible conflicts, valuing working with others, assessing the effectiveness of a team and presenting the final results.

Teaching methodology

The methodologies used are:
Theoretical sessions (20%), individual working problems (10%) and team-working in laboratory sessions (10%).

Learning objectives of the subject

1. To know and apply the frequencial methods in order to determine the stability and to design compensators.
2. To present the tools for modeling and analysis of discrete time systems.
3. To present methods for design of discrete time systems.
4. To show the possibilities and limitations of computers in the control algorithms implementation.
### Study load

<table>
<thead>
<tr>
<th>Activity</th>
<th>Hours</th>
<th>Percentage</th>
</tr>
</thead>
<tbody>
<tr>
<td>Total learning time</td>
<td>150h</td>
<td></td>
</tr>
<tr>
<td>Hours large group</td>
<td>45h</td>
<td>30.00%</td>
</tr>
<tr>
<td>Hours medium group</td>
<td>0h</td>
<td>0.00%</td>
</tr>
<tr>
<td>Hours small group</td>
<td>15h</td>
<td>10.00%</td>
</tr>
<tr>
<td>Guided activities</td>
<td>0h</td>
<td>0.00%</td>
</tr>
<tr>
<td>Self study</td>
<td>90h</td>
<td>60.00%</td>
</tr>
</tbody>
</table>
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## Content

<table>
<thead>
<tr>
<th>1. Stability in frequency domain of continuous time systems.</th>
<th><strong>Learning time:</strong> 25h</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Description:</strong> To know all the graphical methods concerned with frequencial response, in order to apply the general stability criterion.</td>
<td>Theory classes: 7h 30m</td>
</tr>
<tr>
<td><strong>Related activities:</strong> Problem solving sessions.</td>
<td>Laboratory classes: 2h 30m</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>2. Design and compensation of control systems by frecuencial methods.</th>
<th><strong>Learning time:</strong> 10h</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Description:</strong> Design of lead compensators and lag compensators using frecuencial methods.</td>
<td>Theory classes: 3h</td>
</tr>
<tr>
<td><strong>Related activities:</strong> Problem solving sessions.</td>
<td>Laboratory classes: 1h</td>
</tr>
<tr>
<td><strong>Specific objectives:</strong> To apply the lag and lead compensation technics. To know the advantages and drawbacks of this compensation technics.</td>
<td>Self study: 6h</td>
</tr>
</tbody>
</table>
### 3. Introduction to digital control of dynamic systems.

**Learning time:** 10h  
Theory classes: 3h  
Laboratory classes: 1h  
Self study: 6h

**Description:**
To describe the functions and characteristics of the elements and signals belonging to a computer controlled system.

**Related activities:**
Problem solving sessions.

**Specific objectives:**
To consider the effect of the presence of sampled data signals in the control loop and to know the problems associated with the choice of the sampling period, and Shannon's theorem.

### 4. The z-transform.

**Learning time:** 15h  
Theory classes: 4h 30m  
Laboratory classes: 1h 30m  
Self study: 9h

**Description:**
Introduction to the z-transform in order to represent signals of sampled data systems.

### 5. Stability of sampled data systems.

**Learning time:** 10h  
Theory classes: 3h  
Laboratory classes: 1h  
Self study: 6h

**Description:**
Study of the stability of sampled data systems.

**Specific objectives:**

### 6. Design of digital controllers.

**Learning time:** 30h  
Theory classes: 9h  
Laboratory classes: 3h  
Self study: 18h

**Specific objectives:**
### 7. State model of discrete systems.

**Learning time:** 20h  
Theory classes: 6h  
Laboratory classes: 2h  
Self study: 12h

**Description:**  
To obtain models of discrete time systems in the state space.

**Specific objectives:**  
State model of discrete systems. Discrete time state equation solution. Discretization of the state equation of continuous time systems.

### 8. State space control.

**Learning time:** 30h  
Theory classes: 9h  
Laboratory classes: 3h  
Self study: 18h

**Specific objectives:**  

### Qualification system

Partial controls (2): 30%  
Last control: 40%  
Practices: 15%  
Exercises / problems: 15%  
Other tests / projects: 35%  
Generic competition, self-directed learning, represents 15% of the global evaluation.
Bibliography

Basic:


Complementary:
