



Guía docente

300107 - CONTROL - Teoría de Sistemas de Control e Ingeniería de Control

Última modificación: 22/01/2026

Unidad responsable: Escuela de Ingeniería de Telecomunicación y Aeroespacial de Castelldefels
Unidad que imparte: **Titulación:** MÁSTER UNIVERSITARIO EN INTELIGENCIA ARTIFICIAL PARA INDUSTRIAS CONECTADAS (AI4CI) (Plan 2025). (Asignatura optativa).

Curso: 2025 **Créditos ECTS:** 4.0 **Idiomas:** Inglés

PROFESORADO

Profesorado responsable: Soenke Rhein (Univ. Ulm)
Mylene Pischella (CNAM Paris)
Steffen Moser (Univ. Ulm)
Juan Carlos Aguado (UPC)

Otros:

CAPACIDADES PREVIAS

- Fundamentals of higher mathematics, especially linear algebra
- Fundamentals of signals and systems
- Basic design methods for LTI systems in frequency domain
- Description of linear, time-invariant systems in time and frequency domain,
- Laplace transform, analysis of LTI systems (Bode and Nyquist plots)

METODOLOGÍAS DOCENTES

Online lectures and activities

OBJETIVOS DE APRENDIZAJE DE LA ASIGNATURA

Students are able to discuss control theory in time domain. They are capable of applying the methods of model-based control theory of linear and non-linear systems. To an increasing degree, requirements on safety, sustainability and economic feasibility of technical products and production plants call for modern approaches of control-theory-based methods. Especially in the environment of control theory, simple and heuristically designed controllers have been reaching their limits. Systematic design of model-based controllers in the time domain allows considering of non-linearities and has the potential to achieve significantly improved controller results. Students are able to describe the necessary mathematics and system-theory basics. They are able to analyze time-continuous systems in the time domain. They are able to categorize systems according to system-theoretic properties. Further, they have the ability to apply formal methods in order to design controllers in time domain. They are also able to apply methods for designing controllers for non-linear systems and are capable of managing its operation.

HORAS TOTALES DE DEDICACIÓN DEL ESTUDIANTADO

| Tipo | Horas | Porcentaje |
|----------------------------|-------|------------|
| Horas aprendizaje autónomo | 64,0 | 64.00 |
| Horas grupo grande | 36,0 | 36.00 |

Dedicación total: 100 h



CONTENIDOS

Control System Theory and Control Engineering

Descripción:

- Linear and non-linear time-continuous systems in state space
- Linearization and general solution of linear differential equations of states
- Structural properties of LTI systems in state space (stability, controllability, observability)
- Design of state controllers and state observers for linear systems
- Analysis of non-linear systems (Lyapunov-stability)
- Control and feedback control of non-linear systems

Dedicación: 100h

Grupo grande/Teoría: 36h

Aprendizaje autónomo: 64h

SISTEMA DE CALIFICACIÓN

Exams