

# Course guide 270745 - NTR - New Trends in Robotics

Last modified: 16/07/2024

Unit in charge:	Barcelona School of Informatics
Teaching unit:	1042 - URV - Universitat Rovira i Virgili.
Degree:	MASTER'S DEGREE IN ARTIFICIAL INTELLIGENCE (Syllabus 2017). (Optional subject).

Academic year: 2024	ECTS Credits: 3.0	Languages: English
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### **LECTURER**

Coordinating lecturer:	ALBERT OLLER PUJOL	
Others:	Primer quadrimestre: ALBERT OLLER PUJOL - 10	

### **PRIOR SKILLS**

No previous specific competences are required

## **TEACHING METHODOLOGY**

For each AI methodology: Week-1. Classroom slides and paper introduction (by teacher) Week-2. Homework: paper reading Week-3. Paper discussion in classroom Week-4. Report writing Week-5. Oral presentation. Next paper introduction (by teacher)

## LEARNING OBJECTIVES OF THE SUBJECT

1. Probabilistic techniques applied in robotics

2.Search techniques are applied in robotics

3. Decision making techniques applied in robotics

## **STUDY LOAD**

Туре	Hours	Percentage
Hours large group	27,0	36.00
Self study	48,0	64.00

Total learning time: 75 h

#### CONTENTS

#### **Probabilistic techniques**

#### **Description:**

Probabilistic techniques actually applied in robotics



### Search techniques

#### **Description:**

Search techniques actually applied in robotics

## **Decision making techniques**

#### **Description:**

Decision making techniques actually applied in robotics

#### ACTIVITIES

#### Paper discussion: probabilistic methods

Specific objectives: 1

Full-or-part-time: 25h Self study: 16h Theory classes: 6h Laboratory classes: 3h

#### Paper discussion: search methods

**Specific objectives:** 2

Full-or-part-time: 25h Self study: 16h Theory classes: 6h Laboratory classes: 3h

#### Paper discussion: decision making methods

Specific objectives: 3

Full-or-part-time: 25h Self study: 16h Theory classes: 6h Laboratory classes: 3h

## **GRADING SYSTEM**

Report of Probabilistic methods 33% Report of Search methods 33% Report of Decision Making methods 33%



## **BIBLIOGRAPHY**

#### **Complementary:**

- Múltiple authors. Scientific papers will be provided.