Course guides
220072 - 220072 - Advanced Control Systems

Unit in charge: Terrassa School of Industrial, Aerospace and Audiovisual Engineering
Teaching unit: 707 - ESAII - Department of Automatic Control.

Degree:
- BACHELOR’S DEGREE IN ELECTRICAL ENGINEERING (Syllabus 2009). (Optional subject).
- BACHELOR’S DEGREE IN INDUSTRIAL ELECTRONICS AND AUTOMATIC CONTROL ENGINEERING (Syllabus 2009). (Optional subject).
- BACHELOR’S DEGREE IN AEROSPACE TECHNOLOGY ENGINEERING (Syllabus 2010). (Optional subject).
- BACHELOR’S DEGREE IN AEROSPACE VEHICLE ENGINEERING (Syllabus 2010). (Optional subject).
- BACHELOR’S DEGREE IN INDUSTRIAL TECHNOLOGY ENGINEERING (Syllabus 2010). (Optional subject).

Academic year: 2021  ECTS Credits: 3.0  Languages: English

LECTURER

Coordinating lecturer: Masip Alvarez, Albert
Others: Cayero Becerra, Julián Francisco

PRIOR SKILLS

This course requires the student to have basic skills in:
- Modelling of dynamic systems and transfer function
- Control techniques (PID tuning)

TEACHING METHODOLOGY

The course is divided into parts:
- Theory classes
- Laboratory sessions
- Self-study for doing exercises and activities.

In the theory classes, teachers will introduce the theoretical basis of the concepts, methods and results and illustrate them with examples appropriate to facilitate their understanding.

In the lab sessions, teachers guide students in applying theoretical concepts to solve problems, always using critical reasoning. We propose that students solve two autonomous robot control projects in and outside the classroom, to promote contact and use the basic tools needed to solve problems.

Students, independently, need to work on the materials provided by teachers in order to fix and assimilate the concepts.

The teachers provide the syllabus and monitoring of activities (by ATENEA).

LEARNING OBJECTIVES OF THE SUBJECT

This course is about autonomous mobile robots as seen from the control point of view. The main types of mobile robots (ground, aerial and underwater) are reviewed and their common control architecture is presented. This architecture introduces four control problem categories which are examined (planning, navigation, perception and control). The course is about the control problems and the control tools to solve some of them.

One of the main objectives of the course is to acquire a hands-on experience, which will be obtained through the robotic control projects.

The principal tools of advanced control system design are introduced in the theory lectures and applied in the lab. These tools are the operational aspects of discrete control theory and the state space representation and analysis framework, which allows the natural introduction of advanced control techniques, such as optimal control, model predictive control, etc.
STUDY LOAD

<table>
<thead>
<tr>
<th>Type</th>
<th>Hours</th>
<th>Percentage</th>
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<tbody>
<tr>
<td>Self study</td>
<td>45,0</td>
<td>60.00</td>
</tr>
<tr>
<td>Hours large group</td>
<td>30,0</td>
<td>40.00</td>
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Total learning time: 75 h

CONTENTS

Module 1: Basics for Drone manoeuvring

Description:
Drone flight principles
AR-Drone architecture (soft+hard) Matlab,coms,fisica
ROS basics/fundamentals
AR-Drone simulation model

Specific objectives:

Related activities:
1, 2, 3

Full-or-part-time: 25h
Theory classes: 10h
Self study: 15h

Module 2: Identification and controller design

Description:
Models for control: transfer functions
Identification of transfer functions from experimental data
Controller design based on pole placement using transfer functions
Cascade control structure

Related activities:
1, 2, 3

Full-or-part-time: 25h
Theory classes: 10h
Self study: 15h

Mission control

Description:
Image processing
Path tracking algorithm
State machines

Related activities:
1, 2, 3

Full-or-part-time: 25h
Theory classes: 10h
Self study: 15h
ACTIVITIES

1. Theory lectures

Description:
Exposition of the subject theory contents.

Specific objectives:
Knowledge transfer, creation of a conceptual reference frame, solving questions and generating interest about the subject.

Material:
Slide compilations and handouts at Atenea
General bibliography of the subject

Full-or-part-time: 10h
Theory classes: 10h

2. Laboratory projects

Description:
Students, in groups, follow the instructions to resolve a practical control problem. These sessions take place at the lab and there are two problems to solve. Terrestrial and aerial mobile robots are the platforms used in the projects developed in the lab sessions.

Specific objectives:
Proper application of control design methodology.

Material:
Project instructions at Atenea
Simulation software (Matlab)
Lab plants (aerial and mobile robots)
Course handouts and notes

Delivery:
Each group has to deliver a report describing the results of the projects, the methodology and techniques applied to obtain the final results. A practical demonstrations is also required.

Full-or-part-time: 53h
Theory classes: 18h
Self study: 35h
3. Final examination

Description:
Written individual examination about the concepts of theory modules. The examination includes conceptual questions, test questions, and problems to be solved by hand.

Specific objectives:
Assess the knowledge acquisition of activities 1, 2. Distinguish from the group evaluation in activity 2.

Material:
Examination instructions.

Delivery:
Answers to the questions and solutions to the problems posed in the instructions.

Full-or-part-time: 12h
Theory classes: 2h
Self study: 10h

GRADING SYSTEM

Individual exam: 40%
Lab deliveries: 60%
The students who do not pass the subject can take an additional global written exam that will take place the date stated in the calendar of final exams. The grade obtained in this exam will replace the one of the final exam in case it is higher. The maximum final mark in this case will be 5.0

BIBLIOGRAPHY

Basic: