230121 - EPSC - Power Electronics and Control Systems

Coordinating unit: 230 - ETSETB - Barcelona School of Telecommunications Engineering
Teaching unit: 710 - EEL - Department of Electronic Engineering
Academic year: 2018
Degree: BACHELOR’S DEGREE IN TELECOMMUNICATIONS TECHNOLOGIES AND SERVICES ENGINEERING (Syllabus 2015). (Teaching unit Optional)
ECTS credits: 7

Teaching languages: Spanish, English

Teaching staff

Coordinator: Biel Sole, Domingo
Guinjoan Gispert, Francisco Juan

Others: Biel Sole, Domingo
Guinjoan Gispert, Francesc
Dominguez Pumar, Manuel

Degree competences to which the subject contributes

Generical:
10 ECI N3. They will have acquired knowledge related to experiments and laboratory instruments and will be competent in a laboratory environment in the ICC field. They will know how to use the instruments and tools of telecommunications and electronic engineering and how to interpret manuals and specifications. They will be able to evaluate the errors and limitations associated with simulation measures and results.

Teaching methodology

Regular class of theory and problems

Written exams:
1) Mid course exam
2) Final exam

Lab work.

Learning objectives of the subject

Introducing the principles of design of linear control techniques in continuous and discrete time systems and its application to physical systems, focusing in electronic and electromechanical ones

Knowing CAD tools to design and implement controllers to control electronic and electromechanical systems. Applying experimental techniques for the validation of the performance of control systems.

Design oriented analysis, implementation and experimental verification of electrical power conversion circuits and their industrial applications in electronic and electromechanical equipment power supply, communication systems and renewable energy.
## Study load

<table>
<thead>
<tr>
<th>Total learning time: 175h</th>
<th>Hours large group:</th>
<th>52h</th>
<th>29.71%</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Hours small group:</td>
<td>26h</td>
<td>14.86%</td>
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<tr>
<td></td>
<td>Self study:</td>
<td>97h</td>
<td>55.43%</td>
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# Content

<table>
<thead>
<tr>
<th>Introduction to linear control systems</th>
<th>Learning time: 8h</th>
</tr>
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<tbody>
<tr>
<td></td>
<td>Theory classes: 2h</td>
</tr>
<tr>
<td></td>
<td>Laboratory classes: 2h</td>
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<tr>
<td></td>
<td>Self study : 4h</td>
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**Description:**
- Basic components of a control system, reference, control, output and disturbance signals.
- Control system goals.
- Continuous-time control and discrete-time control.
- Dynamic systems classification: linear and nonlinear systems, time-varying and time-invariant systems.
- Transfer function of linear systems.

<table>
<thead>
<tr>
<th>Continuous-time control systems analysis</th>
<th>Learning time: 16h</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Theory classes: 6h</td>
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<tr>
<td></td>
<td>Laboratory classes: 2h</td>
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<tr>
<td></td>
<td>Self study : 8h</td>
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**Description:**
- Transient and steady-state time-response of linear systems.
- First and second-order systems.
- Transient response characterization: settling time, maximum overshoot, etc.
- Higher order systems: transient response approximation through dominant poles and zero-pole cancellation.
- Routh-Hurwitz stability criteria.
- Root locus analysis.
- Steady-state error.

<table>
<thead>
<tr>
<th>Continuous-time control systems design</th>
<th>Learning time: 18h</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Theory classes: 6h</td>
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<tr>
<td></td>
<td>Laboratory classes: 2h</td>
</tr>
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<td></td>
<td>Self study : 10h</td>
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**Description:**
- Control design through root locus.
- First and second-order controllers.
- PID controllers.
- Implementation issues of PID controllers.
## Analysis of control systems in frequency domain

<table>
<thead>
<tr>
<th>Description:</th>
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</table>
| - Frequency response of linear systems.  
- Nyquist diagram and Bode diagram.  
- Relative stability: gain margin and phase margin. |

<table>
<thead>
<tr>
<th>Learning time:</th>
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<tbody>
<tr>
<td>14h</td>
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</tbody>
</table>
| Theory classes: 4h  
Laboratory classes: 2h  
Self study: 8h |

## Frequency-domain control design

<table>
<thead>
<tr>
<th>Description:</th>
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</table>
| - Frequency-domain specifications: relative stability margins and bandwidth of a control system.  
- Lead-lag and phase-lag compensations. |

<table>
<thead>
<tr>
<th>Learning time:</th>
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<tbody>
<tr>
<td>16h</td>
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</table>
| Theory classes: 4h  
Laboratory classes: 2h  
Self study: 10h |

## Discrete-time control systems

<table>
<thead>
<tr>
<th>Description:</th>
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</table>
| - Introduction to discrete-time control systems.  
- The Z transform.  
- Z Plane analysis of discrete-time systems.  
- Design of discrete-time control systems by conventional methods. |

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<thead>
<tr>
<th>Learning time:</th>
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<tbody>
<tr>
<td>16h</td>
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</table>
| Theory classes: 4h  
Laboratory classes: 3h  
Self study: 9h |

## Introduction to Power Electronics: power conversion circuits

<table>
<thead>
<tr>
<th>Description:</th>
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<tbody>
<tr>
<td>Sources, loads and storage systems electrical characteristics. Power conversion types. Elemental power conversion circuits. Power devices and ancillary circuits.</td>
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<table>
<thead>
<tr>
<th>Learning time:</th>
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<tbody>
<tr>
<td>9h</td>
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</tbody>
</table>
| Theory classes: 3h  
Laboratory classes: 0h  
Self study: 6h |
### Steady-state analysis and design of power converters

**Description:**
Steady-state specifications of power converters. Components design.

**Learning time:** 24h
- Theory classes: 7h
- Laboratory classes: 4h
- Self study: 13h

### Dynamical modelling and control of power converters

**Description:**
Controlled sources modelling of switches. PWM modelling. Transfer functions and control design.

**Learning time:** 23h
- Theory classes: 7h
- Laboratory classes: 4h
- Self study: 12h

### Modelling and design of magnetic devices

**Description:**
Equivalent magnetic circuits. Reluctance and gap concept. Inductors and transformers design.

**Learning time:** 9h
- Theory classes: 3h
- Laboratory classes: 1h
- Self study: 5h

### Applications of power electronics: power supply of electronic devices, communications, renewable energy based systems.

**Description:**
Switching regulators design for electronic devices power supply. Battery chargers, photovoltaic applications.

**Learning time:** 22h
- Theory classes: 6h
- Laboratory classes: 4h
- Self study: 12h
Qualification system

Written exams:
1) Mid course exam
2) Final exam

Lab work: evaluation of lab work

Final Mark = 0.3*(lab work) + 0.7 max {Final Exam Mark; 0.7*Final Exam Mark + 0.3*Mid Course Exam Mark}

This course will also assess on the following skills:
- Ability to identify, state and solve engineering problems (High level)
- Instrumentation knowledge and experimental skills (High level)

Bibliography

Basic:


