230641 - PCP - Power Control and Processing

Coordinating unit: 230 - ETSETB - Barcelona School of Telecommunications Engineering
Teaching unit: 710 - EEL - Department of Electronic Engineering
Academic year: 2019
Degree: MASTER'S DEGREE IN ELECTRONIC ENGINEERING (Syllabus 2013). (Teaching unit Compulsory)
MASTER'S DEGREE IN ADVANCED TELECOMMUNICATION TECHNOLOGIES (Syllabus 2019). (Teaching unit Optional)
MASTER'S DEGREE IN TELECOMMUNICATIONS ENGINEERING (Syllabus 2013). (Teaching unit Optional)
MASTER'S DEGREE IN ELECTRONIC ENGINEERING (Syllabus 2009). (Teaching unit Optional)
ECTS credits: 5
Teaching languages: English

Teaching staff
Coordinator: DOMINGO BIEL, FRANCESC GUINJOAN
Others: ALBERTO POVEDA, EDUARD ALARCÓN

Prior skills
Basic knowledge on linear control systems and power electronics

Degree competences to which the subject contributes

Specific:
1. Ability to understand and apply the principles of operation of power electronic systems in regulation, undulation and amplification applications.
2. Ability to understand and apply the principles of operation of the current control method and its application to battery charging, supply for LED lighting, power factor correction, and "Low Power supplies"
3. Ability to apply state control techniques to the design of controllers for power electronic systems.
4. Ability to design continuous and discrete time controllers for power electronic systems.

Transversal:
5. EFFECTIVE USE OF INFORMATION RESOURCES: Managing the acquisition, structuring, analysis and display of data and information in the chosen area of specialisation and critically assessing the results obtained.
6. FOREIGN LANGUAGE: Achieving a level of spoken and written proficiency in a foreign language, preferably English, that meets the needs of the profession and the labour market.

Teaching methodology
- Lectures
- Exercises
- Other activities

Learning objectives of the subject

Learning objectives of the subject:

The aim of this course is to introduce the students in several techniques of modelling, design and control of power
processing systems for regulation, wide-band amplification and waveform generation in different applications.

Requisites: Students coming from academic studies other than B. Sc. Electronics Systems Engineering or equivalent ones, should have successfully passed the examinations of the bridging courses "Control" and "POT".

Learning results of the subject:

- Ability to derive state models of switching power converter circuits.
- Ability to design and verify the features, by numerical simulation, of state linear controllers for switching power converters in amplification, regulation and waveform generation applications.
- Ability to identify the design restrictions involved in the digital implementation of continuous time controllers for switching power converters.

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<thead>
<tr>
<th>Study load</th>
<th>Total learning time: 125h</th>
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<tbody>
<tr>
<td>Hours large group:</td>
<td>39h</td>
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<tr>
<td>Hours medium group:</td>
<td>0h</td>
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<tr>
<td>Hours small group:</td>
<td>0h</td>
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<td>Guided activities:</td>
<td>0h</td>
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<tr>
<td>Self study:</td>
<td>86h</td>
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## Content

<table>
<thead>
<tr>
<th>Section</th>
<th>Learning time: 10h</th>
<th>Description</th>
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</table>
| 1. **Introduction to power processing systems** | Theory classes: 3h | - Circuit elements in high-efficiency power processors  
- Power conversion types  
- Switching power converters  
- Functionalities and control requirements: regulation, amplification and waveform generation. |
| | Self study: 7h | |

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<tr>
<th>Section</th>
<th>Learning time: 25h</th>
<th>Description</th>
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| 2. **Switching converters modelling** | Theory classes: 7h | - State-space description of dynamical systems  
- Dynamical systems classification (linear and nonlinear systems, time-varying and time-invariant systems, SISO and MIMO systems)  
- State-space models of switching power converters: nonlinear and linearized models.  
  - Steady-state behaviour. Equilibrium points.  
  - Linearized dynamical behaviour: transfer functions |
| | Self study: 18h | |

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<tr>
<th>Section</th>
<th>Learning time: 44h</th>
<th>Description</th>
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- Output feedback.  
- State feedback. Pole placement design through Ackermann's formula  
- Discrete-time control: analysis and constraints. Implementation issues |
| | Self study: 30h | |
4. Control applications in power electronics

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<tr>
<th>Learning time: 46h</th>
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<tr>
<td>Theory classes: 15h</td>
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<tr>
<td>Self study: 31h</td>
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**Description:**
- Output feedback and state feedback in switching power regulators
- Control of grid-connected inverters
- Power factor correction and battery chargers.
- Wide-band amplifiers
- Current control for switching power regulators

**Planning of activities**

**LECTURES**

**EXERCISES**

**Description:**
Exercises to strengthen the theoretical knowledge.

**OTHER ACTIVITIES**

**Description:**
Numerical simulation homework

**EXTENDED ANSWER TEST (FINAL EXAM)**

**Description:**
Final examination.

**Qualification system**

Mid course exam (50%)
Final exam (50%)
Bibliography

Basic:


Complementary: