Degree competences to which the subject contributes

Specific:
CE3. (ENG) Conocimiento de la dinámica del buque y de las estructuras navales, y capacidad para realizar análisis de optimización de la estructura, de la integración de los sistemas a bordo, y del comportamiento del buque en la mar y de su maniobrabilidad.

Transversal:
CT5. THIRD LANGUAGE Learning a third language, preferably English, with adequate oral and written and in line with the future needs of the graduates.

Teaching methodology

MD1. Lectures
MD2. Participative lecturers
MD4. Self-study by solving exercises
MD5. Learning based in problems / projects

Learning objectives of the subject

Acquire a basic knowledge of ship dynamics and how to predict ship motions in advance. Provide information on fundamentals of linear and non-linear ship motion in calm water and in waves. Establish a background of applied methods for description of natural ocean waves and calculation of forces and moments on ship due to sea loads and the resultant ship motion.
### Study load

<table>
<thead>
<tr>
<th>Total learning time: 45h</th>
<th>Hours large group:</th>
<th>45h</th>
<th>100.00%</th>
</tr>
</thead>
</table>

280800 - Ship Dynamics
# Content

<table>
<thead>
<tr>
<th>Chapter</th>
<th>Description</th>
<th>Learning time</th>
<th>Theory classes</th>
<th>Self study</th>
</tr>
</thead>
<tbody>
<tr>
<td>Chapter 1. Mathematical concepts</td>
<td>Basic sea statistics and probabilistic concepts. Significant wave height, wave period and wavelength. Probabilistic projection of the sea waves. Fourier Transform tools to represent a wave height signal.</td>
<td>16h</td>
<td>6h</td>
<td>10h</td>
</tr>
<tr>
<td>Chapter 4. Stabilizer systems</td>
<td>Description of the classification and functionality of the different stabilizer systems. Bilge keels, active roll stabilisers, stabiliser tanks, among others.</td>
<td>8h</td>
<td>3h</td>
<td>5h</td>
</tr>
</tbody>
</table>
### Chapter 5. Seakeeping

**Description:**
Effects in seakeeping: slamming, deck wetness, propeller emergence. Introduces the necessary skills for carry out practices using the simulation program "Maxsurf Motions" successfully.

**Learning time:** 8h  
Theory classes: 3h  
Self study: 5h

### Chapter 6. Ship model experiments

**Description:**
Describe the different types of model experiments used to predict ship manoeuvring behaviour and explain their limitations.

**Learning time:** 16h  
Theory classes: 6h  
Self study: 10h

### Chapter 7. Manoeuvring characteristics and port manoeuvres

**Description:**
Controllability and maneuverability concepts. Explain the principles and conduct of manoeuvring trials. Effect of restricted water on the manoeuvring characteristics of a vessel.

**Learning time:** 16h  
Theory classes: 6h  
Self study: 10h

### Chapter 8. Rudder and propeller effect

**Description:**
Explain the effect of rudder and propeller on manoeuvring of a ship both at low speed and at normal cruising speed. Rudder loads. Rudder design.

**Learning time:** 8h  
Theory classes: 3h  
Self study: 5h
Qualification system

The final score is the sum of the following partial grades:
N_{final} = 0.4 N_{fp} + 0.3 N_{sp} + 0.3 N_{ac}

N_{final}: final score
N_{fp}: first partial exam
N_{sp}: second partial exam
N_{ac}: continuous assessment

Partial exams consist of some issues associated with the learning objectives of the course so that respects the knowledge and understanding concepts, and a set of application exercises. The continuous assessment consists of different activities cumulative and formative character, both individual and group, made during the course.

Regulations for carrying out activities

You can't pass the course if all work activities and continuous assessment are carried out and submitted. If the student does not carry out partial and/or final exam, he or she will be considered as: Not Presented. In any case, the student can use any kind of predesigned form in controls or tests.

Bibliography

Basic:

