



# Course guide

## 295105 - 295II021 - Control Systems

**Last modified:** 27/05/2024

**Unit in charge:** Barcelona East School of Engineering  
**Teaching unit:** 707 - ESAII - Department of Automatic Control.

**Degree:** MASTER'S DEGREE IN INTERDISCIPLINARY AND INNOVATIVE ENGINEERING (Syllabus 2019). (Compulsory subject).

**Academic year:** 2024    **ECTS Credits:** 6.0    **Languages:** English

### LECTURER

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**Coordinating lecturer:** Pere Ponsa

**Others:** Javier Gámiz, Abel Torres, Ramon Vilanova

### PRIOR SKILLS

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This is an intermediate level subject in control systems. For a good understanding, a previous background is required: PID control, MATLAB-SIMULINK software, matrix algebra, ordinary differential equations and process instrumentation.

### REQUIREMENTS

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It is recommended to have passed the subjects "Data acquisition Instrumentation" and "Systems Modeling".

### DEGREE COMPETENCES TO WHICH THE SUBJECT CONTRIBUTES

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**Specific:**

CEMUEII-09. Design, implement and manage automated systems for the control and supervision of processes in engineering.

**Generical:**

CGMUEII-01. Participate in technological innovation projects in multidisciplinary problems, applying mathematical, analytical, scientific, instrumental, technological and management knowledge.

**Transversal:**

05 TEQ. TEAMWORK. Being able to work as a team player, either as a member or as a leader. Contributing to projects pragmatically and responsibly, by reaching commitments in accordance to the resources that are available.

06 URI. EFFECTIVE USE OF INFORMATION RESOURCES. Managing the acquisition, structure, analysis and display of information from the own field of specialization. Taking a critical stance with regard to the results obtained.

03 TLG. THIRD LANGUAGE. Learning a third language, preferably English, to a degree of oral and written fluency that fits in with the future needs of the graduates of each course.

### TEACHING METHODOLOGY

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The methodologies used are:

- Master class
- Seminars
- Case study
- Project based learning



## LEARNING OBJECTIVES OF THE SUBJECT

The purpose of this course is to integrate knowledge and skills in the design, development and performance of processes control in industrial domain. The course establishes the relationship between facilities and equipment, people and management systems. The main part of this subject is understand the automatic control using PID law and its application in industrial process control (motor control, level control, temperature control, industrial robot control, water treatment control). The course applies study cases in industrial context through examples of processes control and environmental management of wastewater plants.

## STUDY LOAD

Type	Hours	Percentage
Self study	96,0	64.00
Hours small group	27,0	18.00
Hours large group	27,0	18.00

**Total learning time:** 150 h

## CONTENTS

### 1. Introduction

**Description:**

1.1 Terminology. Definitions. PI&D Diagrams.

**Specific objectives:**

Know how understand control systems and use of software resources.

**Related activities:**

Master Class. Use of software resources.

VIDEO: MATLAB. How to get started with Control Systems in MATLAB. At URL: <https://youtu.be/MyIJIqVVNr0>, last visited 11 th December 2020.

**Full-or-part-time:** 2h

Theory classes: 1h

Self study : 1h

### 2. PID Control

**Description:**

2.1 Introduction.

2.2 PID controllers.

2.3 Process models: static, dynamics.

2.4 PID design.

2.5 Tuning of PID controllers.

**Specific objectives:**

Learn how link the dynamic model of a system with the control law. Learn how configure the PID control law for various applications.

**Related activities:**

Master class. Case study. Examples, Laboratory practices

**Full-or-part-time:** 20h

Theory classes: 9h

Self study : 11h



### 3. Robot dynamics and control

**Description:**

- 3.1 Structure of industrial robot manipulator.
- 3.2 Lagrange's equations of motion.
- 3.3 Actuator dynamics.
- 3.4 Computed-torque control.
- 3.5 PD-plus gravity control.
- 3.6 MATLAB: Case study: robot 2DoF.
- 3.7 Force control.

**Specific objectives:**

Provide an integrated vision of control of industrial robot manipulators.

**Related activities:**

Master Class. Case study. Examples. Exercises. Use of MATLAB software.

**Full-or-part-time:** 3h

Theory classes: 1h

Self study : 2h

### 4. Industrial control

**Description:**

- 4.1 Introduction
- 4.2 Internal model control.
- 4.3 Cascade control.
- 4.4 Feedforward control.
- 4.5 Time delay compensation.
- 4.6 Multivariable control.

**Specific objectives:**

Learn an integrated vision of industrial control.

**Related activities:**

Master class. Exam. Case study, MATLAB examples.

**Full-or-part-time:** 18h

Theory classes: 10h

Self study : 8h

## 5. Water treatment control

### Description:

- 5.1 Case study: Drinking Water treatment plant.
- 5.2 Case study: Wastewater Treatment plant (WWTP)
- 5.3 Aeration control system
- 5.4 Control strategies (PID fixed gain, PID-Fuzzy control)

### Specific objectives:

General description of the water cycle concept, with special attention to the urban water cycle and its management. All the stages that make up this cycle will be explained and the different characteristics, both of the water and the infrastructures involved from a holistic vision and without forgetting the interrelations between each of stages and their involvement in sustainable resource management within their own cycle.

### Related activities:

Laboratory Practices

### Full-or-part-time: 3h

Theory classes: 1h  
Self study : 2h

## 6. Laboratory practices.

### Description:

PART P1 Practices

- 6.1 PID control with MATLAB-SIMULINK. Obtaining a plant model experimentally.
- 6.2 Implementation of an industrial PID controller for a temperature control process.
- 6.3 Model of level and flow control systems.
- 6.4 Frequency response of level and flow control systems.
- 6.5 PID design of level and flow control systems in academic plant.

PART P2 Practices

- 6.6 Using MATLAB for system identification.
- 6.7 SIMULINK for system identification.
- 6.8 PI controller self tuning for an aeration control system.
- 6.9 Detection of inefficiencies with PID fixed gain
- 6.10 A PID-Fuzzy control approach.

### Specific objectives:

The practical part of the subject contributes to the integration between various software, the acquisition of technical ability in PID control and industrial process control with advanced algorithms.

### Related activities:

In the Laboratory A5.6 Automatic Control is available:

- academic plants for level and flow process control
- MATLAB V. R2018b (or last version)

In the Laboratory A5.4 Automation and Industrial Robotics, is available:

- MATLAB/SIMULINK v. R2018b

At the end of each part of practices, the student's group delivers a report

### Full-or-part-time: 104h

Laboratory classes: 28h  
Self study : 76h

## GRADING SYSTEM

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The qualification system includes activities (written exam) and laboratory practices-  
 $\text{Exam1}*(0,25)+\text{Exam2}*(0,20)+\text{Exercises}*(0,15)+\text{Practices\_1}*(0,20)+\text{Practices\_2}*(0,20)$   
Exam1: Module 2  
Exam2: Modules 4  
Exercises: Module 3  
Practices\_1: Practices 1,2,3,4,5  
Practices\_2: Practices 6,7,8,9,10

## EXAMINATION RULES.

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The Exams are test, exercises.

Laboratory practices are mandatory. Laboratory practices are carried out in groups of 3/4 people in Laboratory A5.6 (PART I) , in Laboratory A5.4 (Part II) or in a Computer Room.

The evaluation method of this course meets the current academic regulations to be qualified: NO REVALUABLE.

## BIBLIOGRAPHY

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### Basic:

- Seborg, Dale E.; Mellichamp, Duncan A.; Doyle III, Francis J.; Edgar, Thomas F. Process Dynamics and Control. Fourth edition. Hoboken, NJ: Wiley, [2017]. ISBN 9781119285915.
- Love, Jonathan. Process automation handbook : a guide to theory and practice. London: Springer, 2007. ISBN 9781846282812.
- Alfaro, Victor M.; Vilanova i Arbós, Ramon. Model-reference robust tuning of PID controllers [on line]. Cham: Springer International, 2016 [Consultation: 24/04/2020]. Available on: <https://dx.doi.org/10.1007/978-3-319-28213-8>. ISBN 9783319282138.
- Reyes Cortés, Fernando. Matlab aplicado a robótica y a mecatrónica. Barcelona: Alfaomega. Marcombo, 2012. ISBN 9788426718365.

### Complementary:

- Ivergård, Toni; Hunts, Brian. Handbook of control room design and ergonomics : a perspective for the future. London ; New York: Taylor & Francis, cop. 2009. ISBN 9781420064292.
- Corke, Peter. Robotics, Vision and Control : Fundamental Algorithms In MATLAB® [on line]. Cham: Springer, 2017 [Consultation: 14/09/2022]. Available on: <https://link-springer-com.recursos.biblioteca.upc.edu/book/10.1007/978-3-319-54413-7>. ISBN 9783319544120.
- Macaulay, T.; Singer, B. Cybersecurity for industrial control systems : SCADA, DCS, PLC, HMI, and SIS. Boca Raton, FL: CRC Press, [2012]. ISBN 9781439801963.
- Dorf, Richard C.; Bishop, Robert H. Modern control systems. 12th ed., international ed. Boston [etc.]: Pearson, cop. 2011. ISBN 9780131383104.

## RESOURCES

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### Other resources:

Magazine Control Engineering: <https://www.controleng.com/magazine>

Introduction to Robotics: <https://pedro-ponsa.staff.upc.edu/> />

International Water Association IWA: <https://www.iwapublishing.com/> />

MATLAB Control Systems Toolbox: <https://es.mathworks.com/help/control/index>