300265 - IMAGE - Applied Image Processing

Coordinating unit: 300 - EETAC - Castelldefels School of Telecommunications and Aerospace Engineering
Teaching unit: 739 - TSC - Department of Signal Theory and Communications
Academic year: 2018
Degree: MASTER'S DEGREE IN APPLIED TELECOMMUNICATIONS AND ENGINEERING MANAGEMENT (MASTEAM) (Syllabus 2015). (Teaching unit Optional)
ECTS credits: 3  
Teaching languages: English

Teaching staff
Coordinator: Francesc Tarrés
Others: Francesc Tarrés

Opening hours
Timetable: Monday 16:00 - 19:00
Tuesday 16:00 -18:00
Thursday 14:30 - 15:30

Prior skills
Signals and Systems, Digital Signal Processing, Digital audiovisual communications fundamentals

Requirements
Pre: No pre-requirements are identified in MASTEAM
Co: No co-requirements are identified in MASTEAM

Degree competences to which the subject contributes

Basic:
CB6. (ENG) CB6 - Poseer y comprender conocimientos que aporten una base u oportunidad de ser originales en el desarrollo y/o aplicación de ideas, a menudo en un contexto de investigación.
CB7. (ENG) CB7 - Que los estudiantes sepan aplicar los conocimientos adquiridos y su capacidad de resolución de problemas en entornos nuevos o poco conocidos dentro de contextos más amplios (o multidisciplinares) relacionados con su área de estudio.

Generical:
03 DIS. (ENG) Diseñar aplicaciones de alto valor añadido basadas en las Tecnologías de la Información y las Comunicaciones (TIC), aplicadas a cualquier ámbito de la sociedad.

Transversal:
03 TLG. THIRD LANGUAGE. Learning a third language, preferably English, to a degree of oral and written fluency that fits in with the future needs of the graduates of each course.
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Teaching methodology

Teaching is based mainly on lectures and some case studies which are analyzed with some detail. Lectures introduce image processing concepts, mathematic tools, algorithms, methods and technologies which are involved in the design of practical image processing and computer vision systems. Lectures are based on a collection of slides and additional notes provided as accompanying hangouts to the lecture.

Every lesson is summarized with a collection of exercises or computer exercises that help the student to summarize the theoretical and practical concepts. Computer exercises are accompanied with practical study cases that the student has to analyze carefully and select the best solution to the problem. Solutions have to developed in high level languages such as Python, OpenCV or Matlab and are presented as guided activities in class. Assessment is evaluated through test questions, exams and reports of case studies solutions.

Learning objectives of the subject

At the end of the course the student should be able to:

To know the technologies and characteristics of camera systems, capture and representation technologies in computer vision systems

Be able to select between different algorithms for extracting the useful information in still images and video. Understand algorithms for image enhancement and segmentation based on local or global features.

Know, understand and be able to select possible alternatives for computer video analysis based on salient feature analysis and other low level descriptors such as color, color, motion and shape.

Understand and be able to use several deep learning architectures and learning algorithms for image classification and object detection.

Have a perspective of different software packages and hardware components for developing customer solutions using computer vision systems.

Study load

<table>
<thead>
<tr>
<th>Total learning time: 74h</th>
<th>Hours large group: 23h</th>
<th>31.08%</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Hours medium group:</td>
<td>0.00%</td>
</tr>
<tr>
<td></td>
<td>Hours small group:</td>
<td>4.05%</td>
</tr>
<tr>
<td></td>
<td>Guided activities:</td>
<td>0.00%</td>
</tr>
<tr>
<td></td>
<td>Self study:</td>
<td>64.86%</td>
</tr>
</tbody>
</table>
## Content

<table>
<thead>
<tr>
<th>Introduction to Digital Image Processing</th>
<th>Learning time: 11h</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Theory classes: 4h</td>
</tr>
<tr>
<td></td>
<td>Self study : 7h</td>
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</tbody>
</table>

**Description:**
Presentation of algorithms and strategies for image enhancement

**Related activities:**
Activity 1, 6, 7

**Specific objectives:**

<table>
<thead>
<tr>
<th>Cameras, Optics and Acquisition Systems</th>
<th>Learning time: 8h</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Theory classes: 3h</td>
</tr>
<tr>
<td></td>
<td>Self study : 5h</td>
</tr>
</tbody>
</table>

**Description:**
Content This chapter introduces some basic principles of image formation and optics to help selection of optical parameters in computer vision applications. A perspective on cameras, illumination and acquisition devices is also provided

**Related activities:**
Activity 2, 6, 7

**Specific objectives:**
Fundamentals of optics. Selecting the optics in different computer vision applications. Types of cameras. Light and principles of lighting in computer vision applications. Types of lighting. Capturing images and video: frame grabbers, digital interfaces.

<table>
<thead>
<tr>
<th>Contour Detection and Segmentation</th>
<th>Learning time: 5h</th>
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</thead>
<tbody>
<tr>
<td></td>
<td>Theory classes: 2h</td>
</tr>
<tr>
<td></td>
<td>Self study : 3h</td>
</tr>
</tbody>
</table>

**Description:**
This chapter covers the classic algorithm for image segmentation based on contour or region analysis. It reviews the main techniques on image segmentation.

**Related activities:**
Activity 3, 6, 7

**Specific objectives:**
Feature Extraction and Its Applications in Computer Vision

Description:
This chapter presents different techniques for extracting automatic features of an image and discusses alternatives for using these features and their descriptors to object detection and recognition.

Related activities:
Activity 4, Activity 7

Specific objectives:
Defining interest points, saliencies, corners, etc. Basic methods for corner extraction: Moravec, Harris, shi-tomasi, Nobles, Trigg, Broen.

Detection of interest points: Kadir & Brady, SUSAN: edge and corner detection, FAST corner detector.

Blob Detection. Laplacian of a Gaussian and Difference of Gaussians. MSER

Scale Invariant Feature Detection (SIFT). SIFT Variants: SURF, GLOH, BRISK, ORB, etc.

Face and person detection. Adaboost and Histogram of Gradients.

Convolutional Neural Networks and Applications to Image Classification and Object Detection

Description:
Fundamentals of neural networks and deep learning are presented in the context of image recognition. The main architectures for image classification and object detection are covered. Examples are presented using Tensorflow or Pytorch developing environments.

Related activities:
Activity 5, Activity 7

Specific objectives:
Evaluation takes into account the following topics

30 % Final Exam  
20 % Control Exam  
20 % Exercises and Computer Exercises Modules 1-2-3  
20 % Exercises and Computer Exercises Modules 4-5  
10 % Participation

Exams consist on short questions, problems and a True/False Quiz.

The exercises and computer exercises have to be presented individually in a report and answering the different questions.

Basic:

