

## Course guide

### 804231 - MAT2VJ - Mathematics II

**Last modified:** 09/09/2025

**Unit in charge:** Image Processing and Multimedia Technology Centre  
**Teaching unit:** 804 - CITM - Image Processing and Multimedia Technology Centre.

**Degree:** BACHELOR'S DEGREE IN VIDEO GAME DESIGN AND DEVELOPMENT (Syllabus 2014). (Compulsory subject).

**Academic year:** 2025    **ECTS Credits:** 6.0    **Languages:** Catalan, English

#### LECTURER

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**Coordinating lecturer:** Angulo Bahon, Cecilio

**Others:** Angulo Bahon, Cecilio  
Sors, Oriol

#### PRIOR SKILLS

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Basic knowledge in linear algebra

#### REQUIREMENTS

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None

#### TEACHING METHODOLOGY

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Lectures, problem-based classes and code practices.

#### LEARNING OBJECTIVES OF THE SUBJECT

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- To describe mathematically the main 2D and 3D geometric objects: points, lines and planes.
- To solve, through the use of mathematics, the possible problems that may arise in the design and development of video games.
- To correctly interpret the conical and cylindrical perspectives.
- To transform geometric objects through displacements, rotations and symmetries.
- To project 3D objects on a plane.
- To properly use the necessary mathematical tools in the resolution of analytical and numerical problems.
- To use geometric constructions with animation trajectories in three-dimensional space.

## STUDY LOAD

Type	Hours	Percentage
Guided activities	10,0	6.67
Hours large group	34,0	22.67
Hours medium group	16,0	10.67
Self study	90,0	60.00

**Total learning time:** 150 h

## CONTENTS

### Vectors. 2D and 3D Geometry

**Description:**

Vectors in  $\mathbb{R}^2$ . Scalar product in  $\mathbb{R}^2$ . Vector product in  $\mathbb{R}^2$ : rotations. Complex numbers.

Vectors in  $\mathbb{R}^3$ . Scalar product in  $\mathbb{R}^3$ . Vector product in  $\mathbb{R}^3$ .

Matrices. Matrices and vector products in  $\mathbb{R}^3$ .

Determinants, inverse and adjoint matrices.

**Full-or-part-time:** 6h

Practical classes: 2h

Self study : 4h

### Differential calculus with several variables

**Description:**

Functions in several variables. 2D objects given by contour lines. 3D objects given by level surfaces.

Vector-valued functions. Parameterized curves. Curvature and torsion.

Functions in several variables with vectorial values. Parameterized surfaces.

Coordinate systems.

**Full-or-part-time:** 8h

Theory classes: 4h

Practical classes: 4h

### Geometric transformations in 2D and 3D

**Description:**

Linear transformations.

Scale transformations.

Orthogonal matrices. Orientation

Rotations. Derivation of the rotation matrix. Euler's theorem.

**Full-or-part-time:** 48h

Theory classes: 10h

Practical classes: 6h

Guided activities: 2h

Self study : 30h

### Geometry for lighting and shading

**Description:**

Blinn-Phong lighting model.

Diffuse reflection. Specular reflection. Reflection of the environment and emissivity.

Tangent space. Calculation of tangent vectors. Construction of relief map.

Normal vector to a surface.

**Full-or-part-time:** 14h

Theory classes: 4h

Practical classes: 2h

Self study : 8h

### Interpolation (I)

**Description:**

Interpolation between two points.

Weighted means and affine combinations.

Three points Interpolations. Barycentric coordinate system.

Bilinear interpolation. Projected convexity's condition. Inverse of bilinear interpolation.

**Full-or-part-time:** 18h

Theory classes: 8h

Practical classes: 2h

Guided activities: 2h

Self study : 6h

### Interpolation (II): Bézier curves, B-Splines, NURBS

**Description:**

Bézier curves.

Particular case of Bézier curves for degree 3.

Method of De Casteljau.

Recursive subdivision.

**Full-or-part-time:** 16h

Theory classes: 6h

Practical classes: 2h

Guided activities: 2h

Self study : 6h

### Ray-Tracing. Intersections

**Description:**

Basic Ray-Tracing

Intersection with rays.

**Full-or-part-time:** 14h

Theory classes: 4h

Practical classes: 2h

Guided activities: 2h

Self study : 6h

### Animation

**Description:**

Animation of position.

"Ease in": fixed object.

"Ease in": moving object.

Application of orientation representations in animation.

**Full-or-part-time:** 8h

Theory classes: 2h

Practical classes: 2h

Self study : 4h

### Kinematics

**Description:**

Articulated rigid joints.

Direct kinematics.

Inverse kinematics.

**Full-or-part-time:** 18h

Theory classes: 8h

Practical classes: 2h

Guided activities: 2h

Self study : 6h

## GRADING SYSTEM

The final qualification will be calculated from the different evaluation items:

- Virtual class exercises (participation and learning attitude): 10%
- Laboratory exercises: 30%
- Project: 15%
- Partial exam: 15%
- Final Exam: 30%

If the pass mark is not obtained, there is the possibility of a reevaluation exam. The qualification of this examen will substitute those of the partial and final exams (45% of the final qualification). The maximum mark to be obtained in the reevaluation is 5.

Irregular actions that may lead to a significant variation of the grade of one or more students constitute a fraudulent performance of an evaluation act. This action entails the descriptive grade of failure and a numerical grade of 0 for the ordinary global evaluation of the course, without the right to re-evaluation.

If the lecturers have indications of the use of AI tools not allowed in the evaluation tests, they may summon the students concerned to an oral test or a meeting to verify the authorship.

## EXAMINATION RULES.

All the activities and deliveries will be mandatory, if not completed they will be graded 0.



## BIBLIOGRAPHY

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### Basic:

- Buss, Samuel R. 3-D computer graphics: a mathematical introduction with OpenGL. Cambridge [etc.]: Cambridge University Press, 2003. ISBN 0521821037.
- Dunn, F.; Parberry, I. 3D math primer for graphics and game development. 2nd ed. Boca Raton, Florida, EUA: CRC Press, 2011. ISBN 9781568817231.
- Gortler, Steven J. Foundations of 3D computer graphics. Cambridge, MA: MIT Press, 2012. ISBN 9780262017350.
- Lengyel, Eric; Smith, Emi. Mathematics for 3D game programming and computer graphics, third edition. 3rd ed. Boston: Cengage Learning, 2011. ISBN 1435458869.